

# Multivariate Bayesian Linear Regression

MLAI Lecture 12

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# Outline

Bayesian Polynomials

# Revisit Olympics Data

- Use Bayesian approach on olympics data with polynomials.
- Choose a prior  $\mathbf{w} \sim \mathcal{N}(\mathbf{0}, \alpha \mathbf{I})$  with  $\alpha = 1$ .
- Choose noise variance  $\sigma^2 = 0.01$

# Sampling the Prior

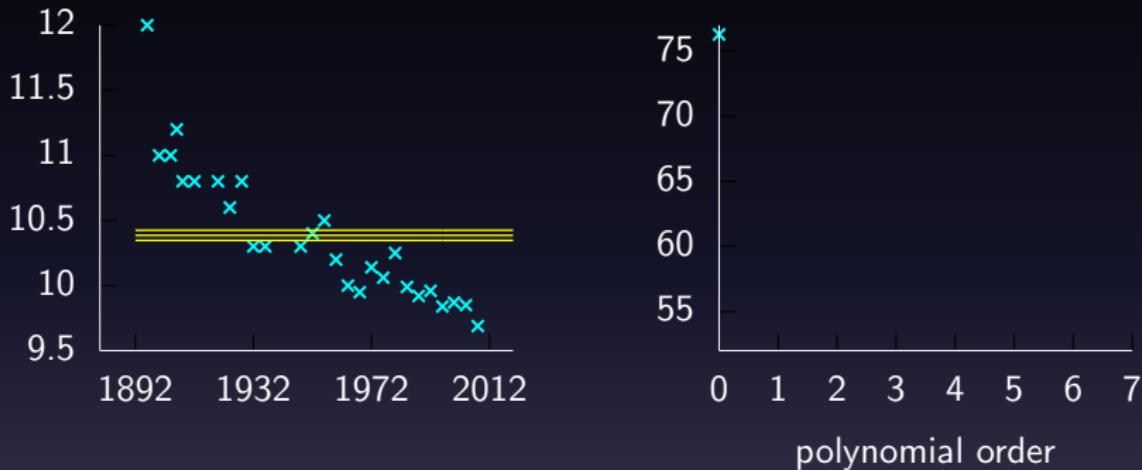
- Always useful to perform a ‘sanity check’ and sample from the prior before observing the data.
- Since  $\mathbf{t} = \Phi\mathbf{w} + \boldsymbol{\epsilon}$  just need to sample

$$\mathbf{w} \sim \mathcal{N}(0, \alpha)$$

$$\boldsymbol{\epsilon} \sim \mathcal{N}(\mathbf{0}, \sigma^2)$$

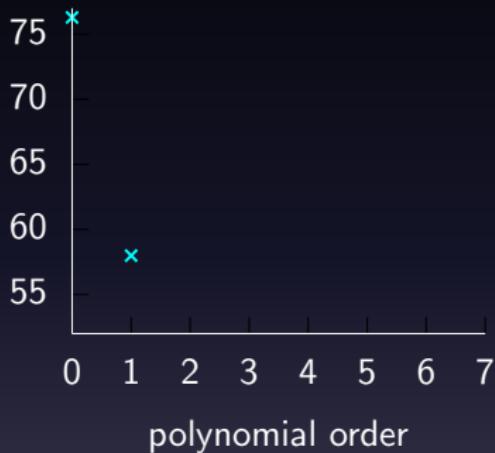
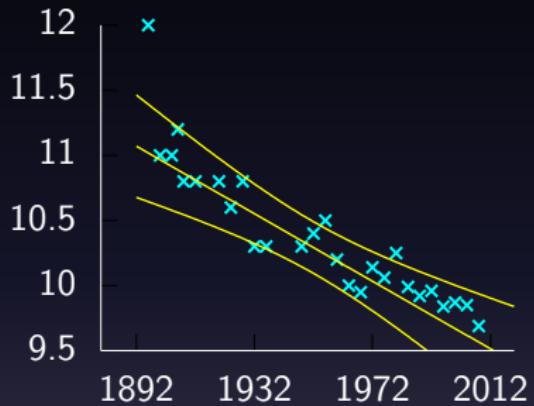
with  $\alpha = 1$  and  $\sigma = 0.01$ .

# Polynomial Fits to Olympics Data



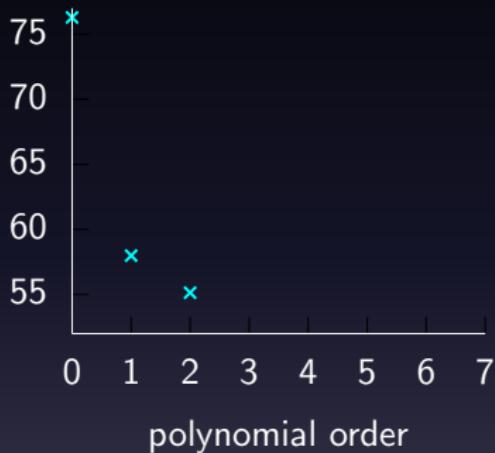
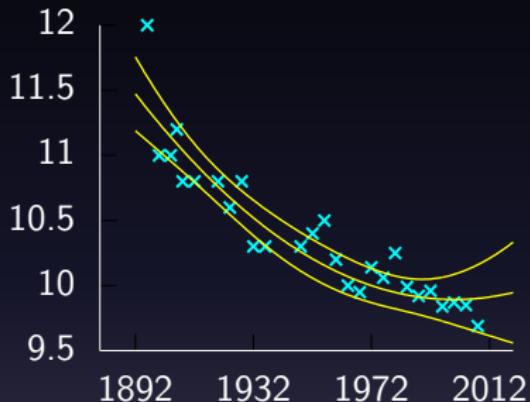
*Left:* fit to data, *Right:* marginal log likelihood. Polynomial order 0, model error 76.292,  $\sigma^2 = 0.268$ ,  $\sigma = 0.518$ .

# Polynomial Fits to Olympics Data



*Left:* fit to data, *Right:* marginal log likelihood. Polynomial order 1, model error 57.991,  $\sigma^2 = 0.0609$ ,  $\sigma = 0.247$ .

# Polynomial Fits to Olympics Data



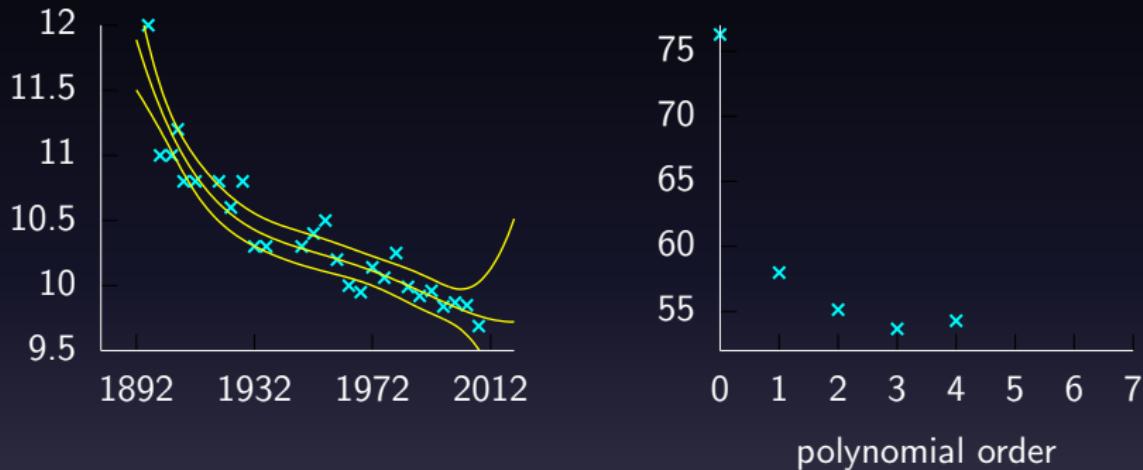
*Left:* fit to data, *Right:* marginal log likelihood. Polynomial order 2, model error 55.155,  $\sigma^2 = 0.0391$ ,  $\sigma = 0.198$ .

# Polynomial Fits to Olympics Data



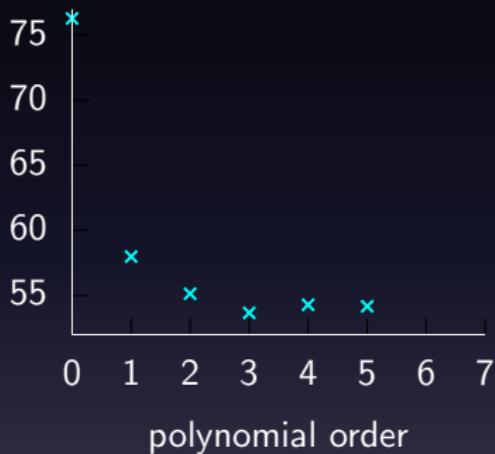
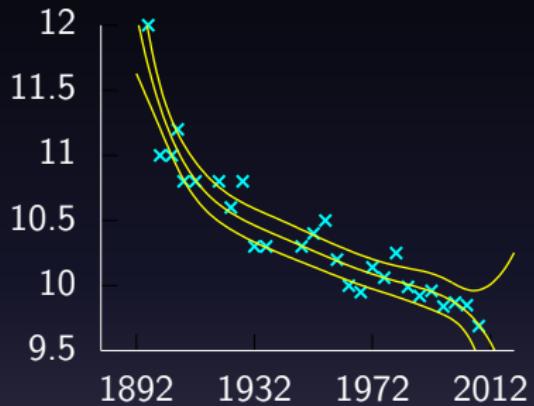
*Left:* fit to data, *Right:* marginal log likelihood. Polynomial order 3, model error 53.683,  $\sigma^2 = 0.0301$ ,  $\sigma = 0.173$ .

# Polynomial Fits to Olympics Data



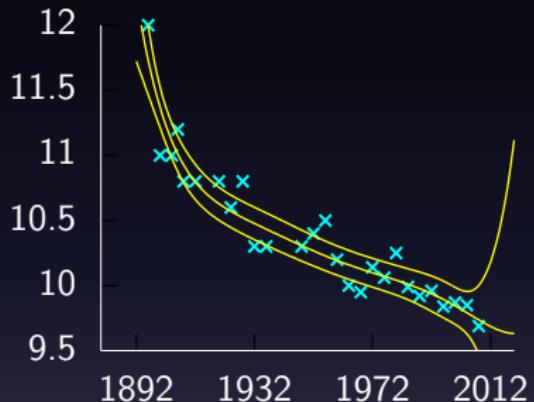
*Left:* fit to data, *Right:* marginal log likelihood. Polynomial order 4, model error 54.301,  $\sigma^2 = 0.0277$ ,  $\sigma = 0.166$ .

# Polynomial Fits to Olympics Data



*Left:* fit to data, *Right:* marginal log likelihood. Polynomial order 5, model error 54.177,  $\sigma^2 = 0.0249$ ,  $\sigma = 0.158$ .

# Polynomial Fits to Olympics Data

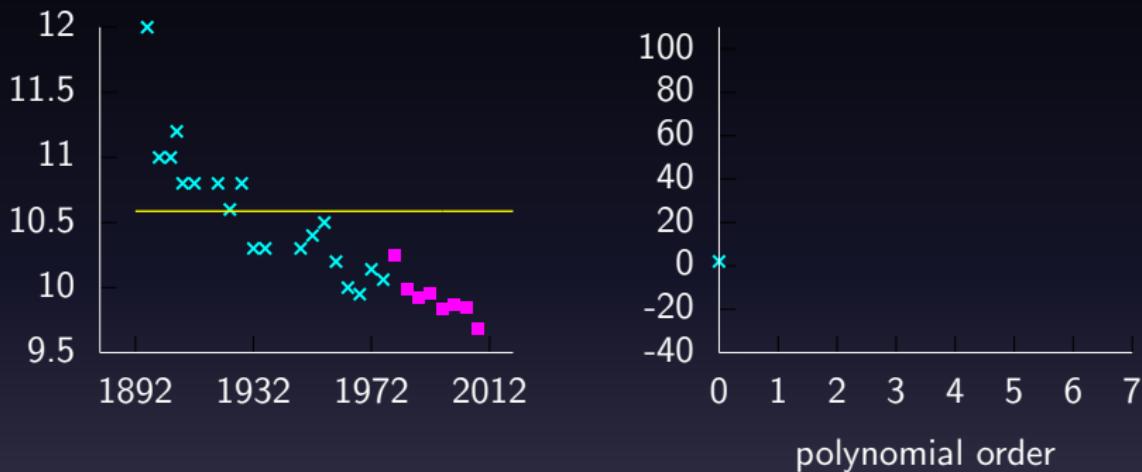


*Left:* fit to data, *Right:* marginal log likelihood. Polynomial order 6, model error 54.415,  $\sigma^2 = 0.0236$ ,  $\sigma = 0.154$ .

# Model Fit

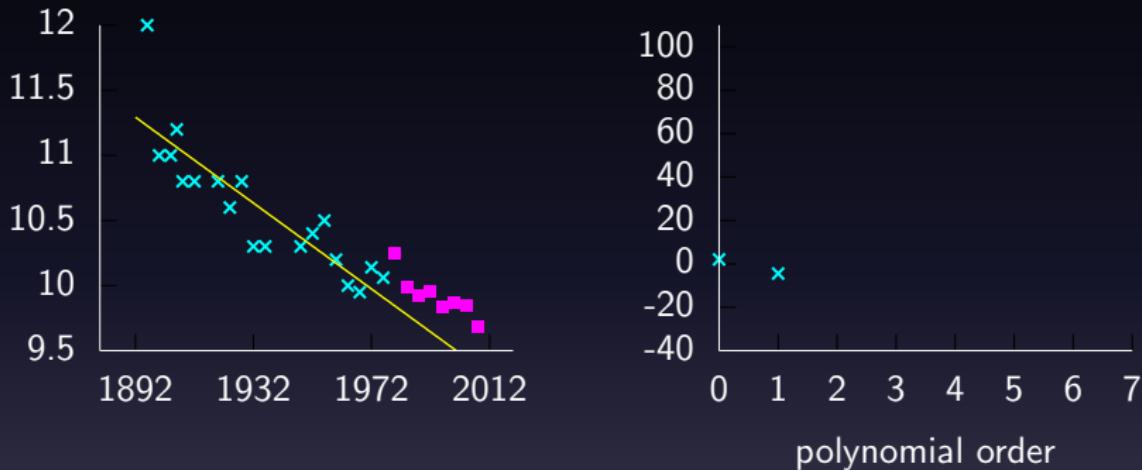
- Marginal likelihood doesn't always increase as model order increases.
- Bayesian model always has 2 parameters, regardless of how many basis functions (and here we didn't even fit them).
- Maximum likelihood model over fits through increasing number of parameters.
- Revisit maximum likelihood solution with validation set.

# Recall: Validation Set for Maximum Likelihood



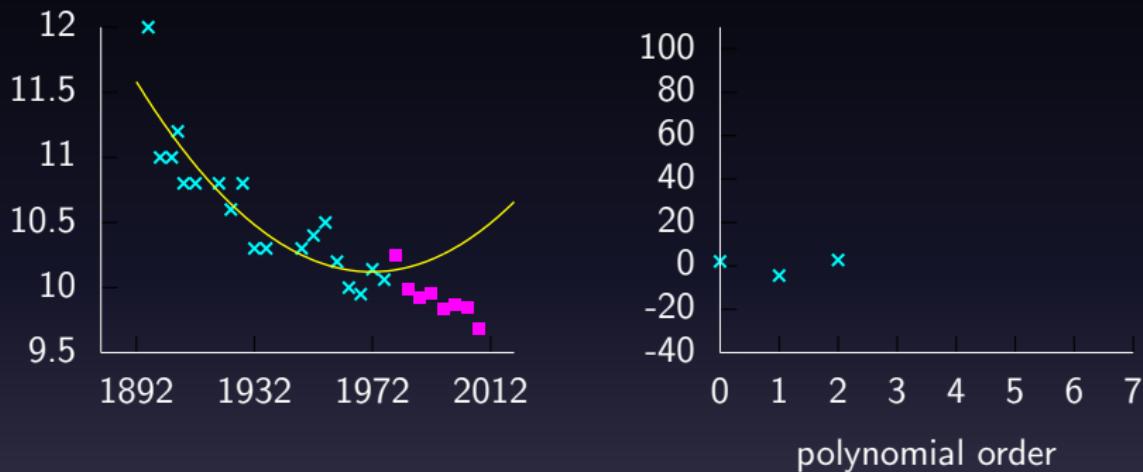
*Left:* fit to data, *Right:* model error. Polynomial order 0, training error -4.0526, validation error 2.0524,  $\sigma^2 = 0.240$ ,  $\sigma = 0.490$ .

# Recall: Validation Set for Maximum Likelihood



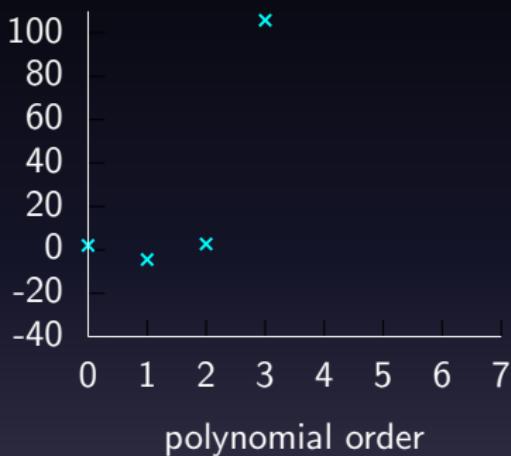
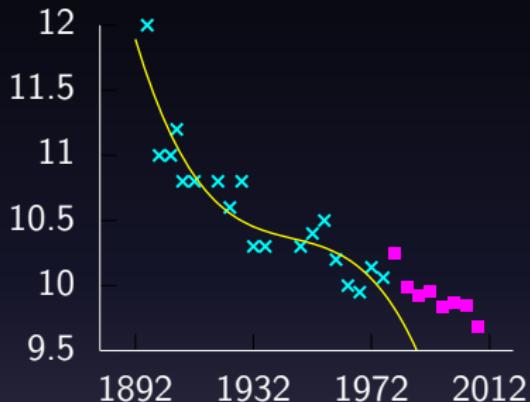
*Left:* fit to data, *Right:* model error. Polynomial order 1, training error -17.519, validation error -4.4127,  $\sigma^2 = 0.0582$ ,  $\sigma = 0.241$ .

# Recall: Validation Set for Maximum Likelihood



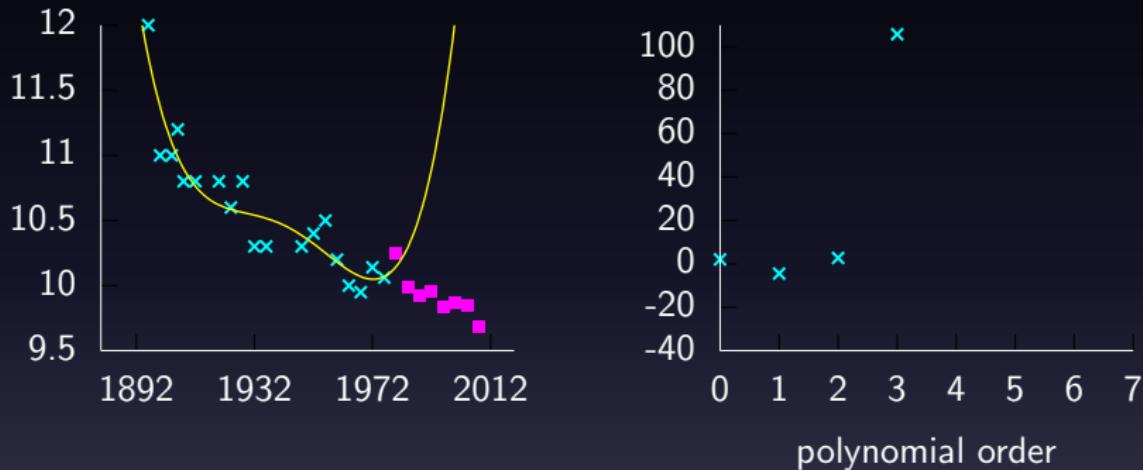
*Left:* fit to data, *Right:* model error. Polynomial order 2, training error -20.159, validation error 2.7275,  $\sigma^2 = 0.0441$ ,  $\sigma = 0.210$ .

# Recall: Validation Set for Maximum Likelihood



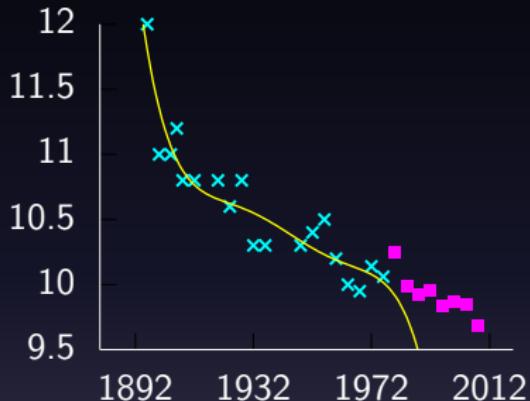
*Left:* fit to data, *Right:* model error. Polynomial order 3, training error -22.172, validation error 105.8,  $\sigma^2 = 0.0357$ ,  $\sigma = 0.189$ .

# Recall: Validation Set for Maximum Likelihood



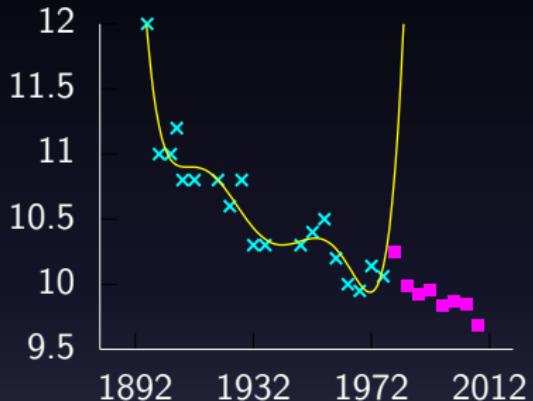
*Left:* fit to data, *Right:* model error. Polynomial order 4, training error -23.781, validation error 578.29,  $\sigma^2 = 0.0301$ ,  $\sigma = 0.173$ .

# Recall: Validation Set for Maximum Likelihood



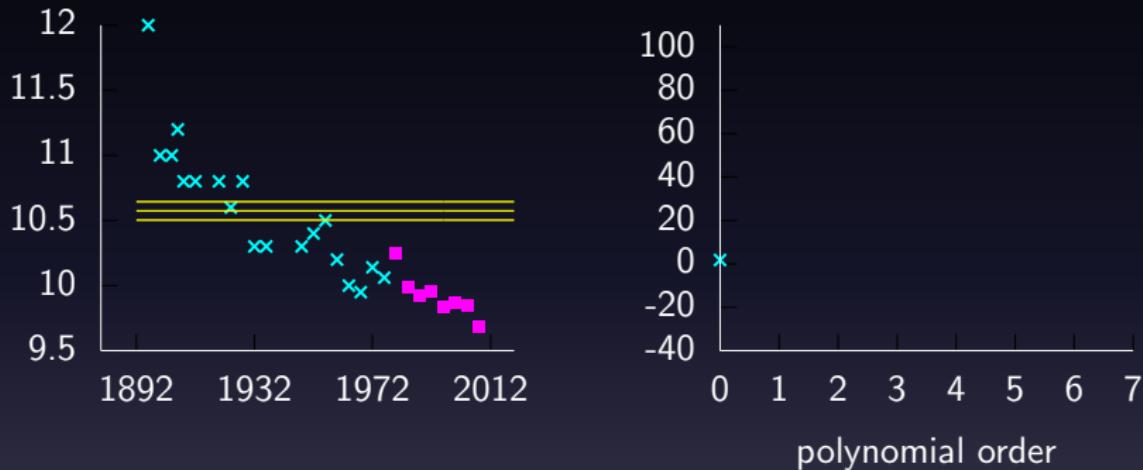
*Left:* fit to data, *Right:* model error. Polynomial order 5, training error -24.136, validation error 746.57,  $\sigma^2 = 0.0290$ ,  $\sigma = 0.170$ .

# Recall: Validation Set for Maximum Likelihood



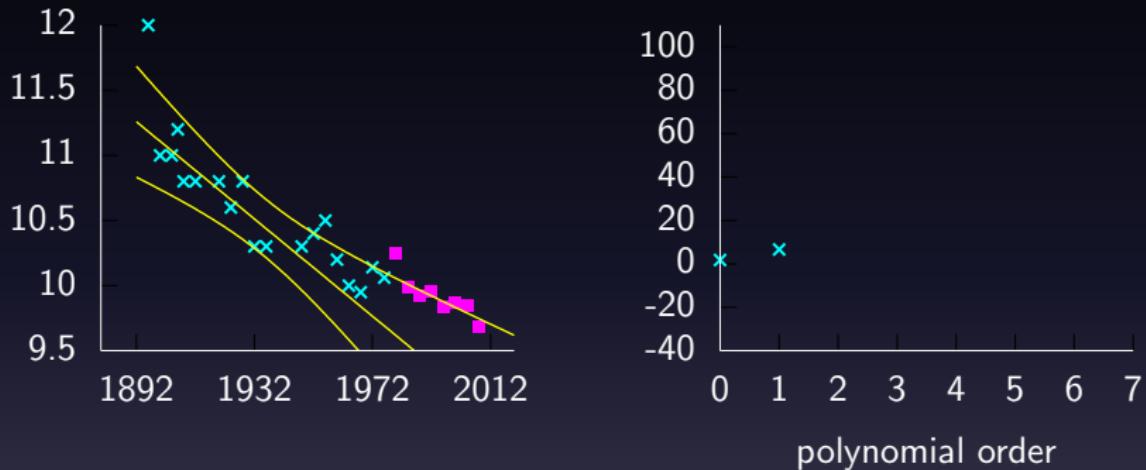
*Left:* fit to data, *Right:* model error. Polynomial order 6, training error -28.528, validation error 3.3585e+05,  $\sigma^2 = 0.0183$ ,  $\sigma = 0.135$ .

# Validation Set



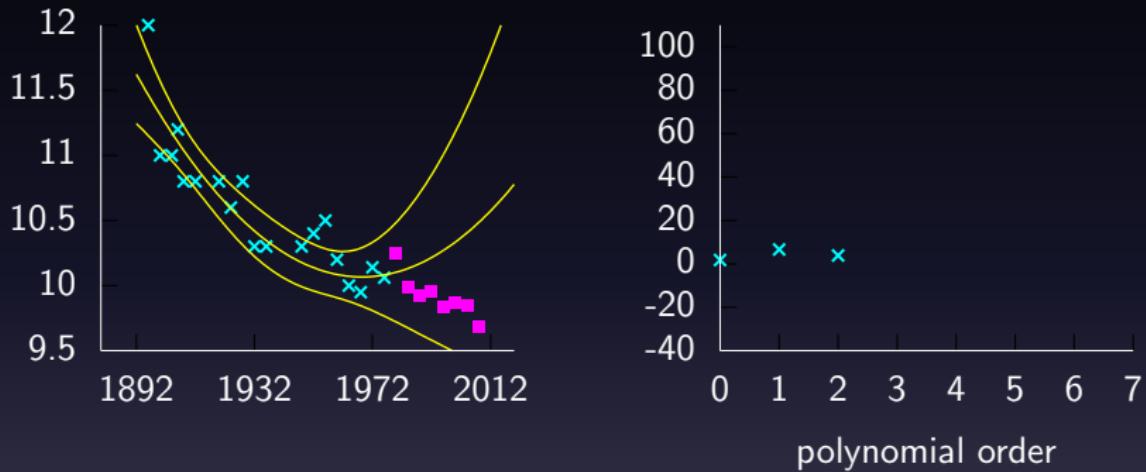
*Left:* fit to data, *Right:* model error. Polynomial order 0, training error 76.292, validation error 1.761,  $\sigma^2 = 0.240$ ,  $\sigma = 0.490$ .

# Validation Set



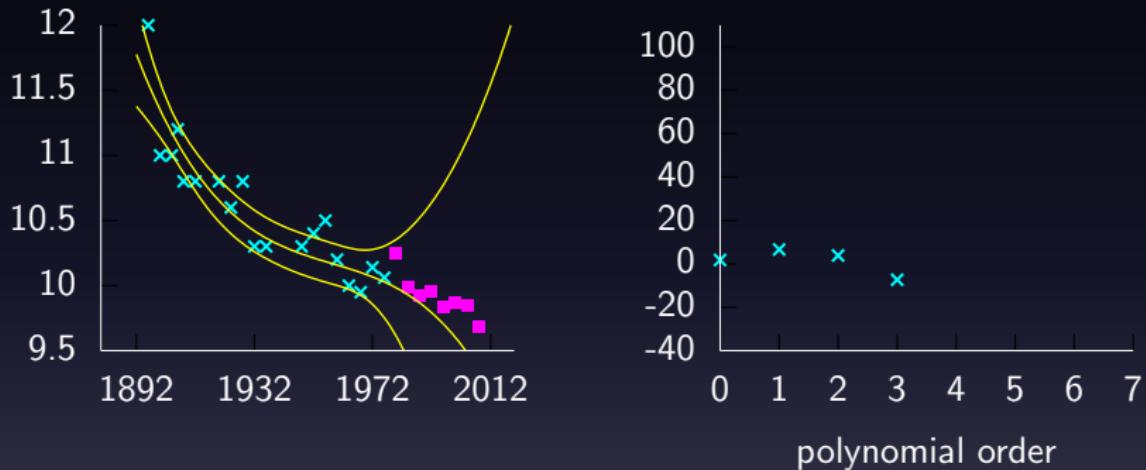
*Left:* fit to data, *Right:* model error. Polynomial order 1, training error 57.991, validation error 6.6482,  $\sigma^2 = 0.0778$ ,  $\sigma = 0.279$ .

# Validation Set



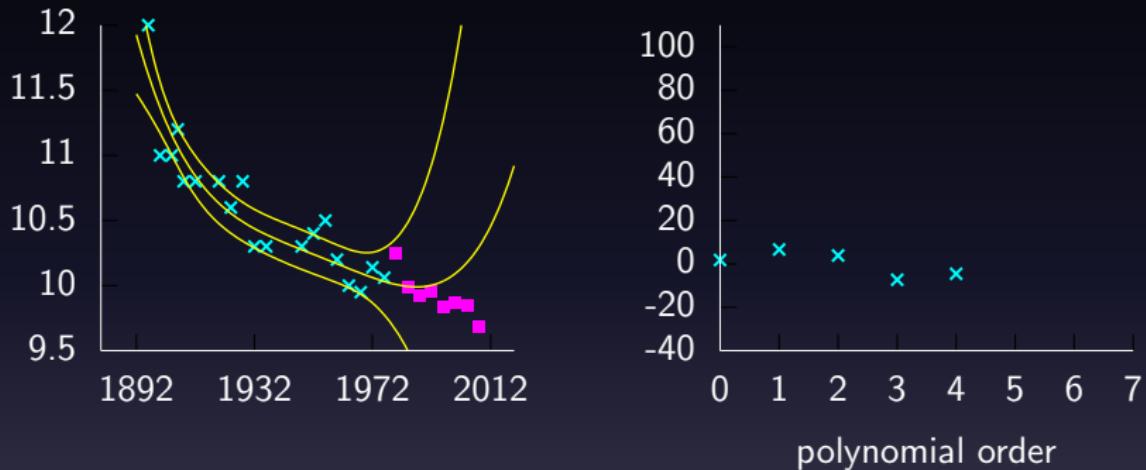
*Left:* fit to data, *Right:* model error. Polynomial order 2, training error 55.155, validation error 3.8897,  $\sigma^2 = 0.0467$ ,  $\sigma = 0.216$ .

# Validation Set



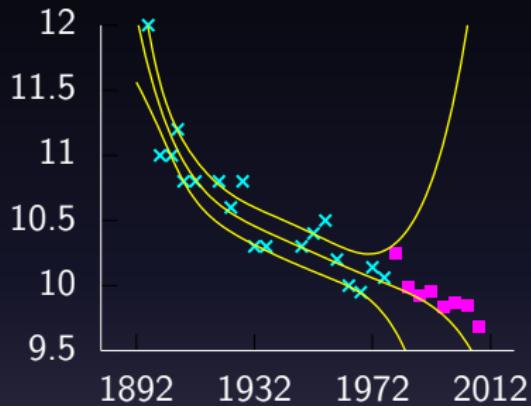
*Left:* fit to data, *Right:* model error. Polynomial order 3, training error 53.683, validation error -7.3484,  $\sigma^2 = 0.0392$ ,  $\sigma = 0.198$ .

# Validation Set



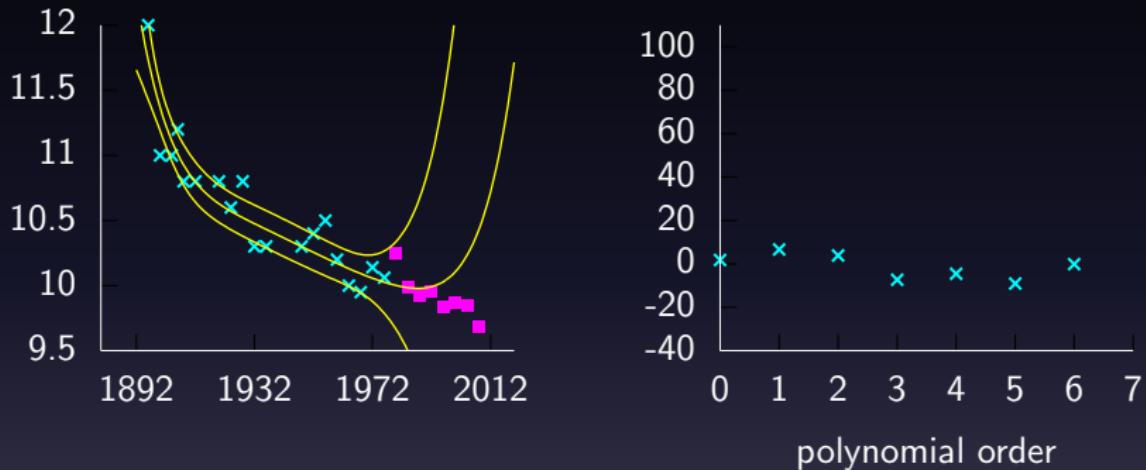
*Left:* fit to data, *Right:* model error. Polynomial order 4, training error 54.301, validation error -4.5232,  $\sigma^2 = 0.0353$ ,  $\sigma = 0.188$ .

# Validation Set



*Left:* fit to data, *Right:* model error. Polynomial order 5, training error 54.177, validation error -9.0875,  $\sigma^2 = 0.0326$ ,  $\sigma = 0.181$ .

# Validation Set



*Left:* fit to data, *Right:* model error. Polynomial order 6, training error 54.415, validation error -0.077841,  $\sigma^2 = 0.0305$ ,  $\sigma = 0.175$ .

# Regularized Mean

- Validation fit here based on mean solution for  $\mathbf{w}$  only.
- For Bayesian solution

$$\boldsymbol{\mu}_w = \left[ \sigma^{-2} \boldsymbol{\Phi}^\top \boldsymbol{\Phi} + \alpha^{-1} \mathbf{I} \right]^{-1} \sigma^{-2} \boldsymbol{\Phi}^\top \mathbf{t}$$

instead of

$$\mathbf{w}^* = \left[ \boldsymbol{\Phi}^\top \boldsymbol{\Phi} \right]^{-1} \boldsymbol{\Phi}^\top \mathbf{t}$$

- Two are equivalent when  $\alpha \rightarrow \infty$ .
- Equivalent to a prior for  $\mathbf{w}$  with infinite variance.
- In other cases  $\alpha \mathbf{I}$  *regularizes* the system (keeps parameters smaller).

# Sampling the Posterior

- Now check samples by extracting  $\mathbf{w}$  from the *posterior*.
- Now for  $\mathbf{t} = \Phi\mathbf{w} + \epsilon$  need

$$\mathbf{w} \sim \mathcal{N}(\boldsymbol{\mu}_w, \mathbf{C}_w)$$

with  $\mathbf{C}_w = [\sigma^{-2}\Phi^\top\Phi + \alpha^{-1}\mathbf{I}]^{-1}$  and  $\boldsymbol{\mu}_w = \mathbf{C}_w\sigma^{-2}\Phi^\top\mathbf{t}$

$$\epsilon \sim \mathcal{N}(\mathbf{0}, \sigma^2)$$

with  $\alpha = 1$  and  $\epsilon = 0.01$ .

# Marginal Likelihood

- The marginal likelihood can also be computed, it has the form:

$$p(\mathbf{t}|\mathbf{X}, \sigma^2, \alpha) = \frac{1}{(2\pi)^{\frac{N}{2}} |\mathbf{K}|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}\mathbf{t}^\top \mathbf{K}^{-1} \mathbf{t}\right)$$

where  $\mathbf{K} = \alpha \Phi \Phi^\top + \sigma^2 \mathbf{I}$ .

- So it is a zero mean  $N$ -dimensional Gaussian with covariance matrix  $\mathbf{K}$ .

# Computing the Expected Output

- Given the posterior for the parameters, how can we compute the expected output at a given location?
- Output of model at location  $\mathbf{x}_i$  is given by

$$y(\mathbf{x}_i; \mathbf{w}) = \boldsymbol{\phi}_i^\top \mathbf{w}$$

- We want the expected output under the posterior density,  $p(\mathbf{w}|\mathbf{t}, \mathbf{X}, \sigma^2, \alpha)$ .
- Mean of mapping function will be given by

$$\begin{aligned}\langle y(\mathbf{x}_i; \mathbf{w}) \rangle_{p(\mathbf{w}|\mathbf{t}, \mathbf{X}, \sigma^2, \alpha)} &= \boldsymbol{\phi}_i^\top \langle \mathbf{w} \rangle_{p(\mathbf{w}|\mathbf{t}, \mathbf{X}, \sigma^2, \alpha)} \\ &= \boldsymbol{\phi}_i^\top \boldsymbol{\mu}_{\mathbf{w}}\end{aligned}$$

# Variance of Expected Output

- Variance of model at location  $\mathbf{x}_i$  is given by

$$\begin{aligned}\text{var}(y(\mathbf{x}_i; \mathbf{w})) &= \langle (y(\mathbf{x}_i; \mathbf{w}))^2 \rangle - \langle y(\mathbf{x}_i; \mathbf{w}) \rangle^2 \\ &= \boldsymbol{\phi}_i^\top \langle \mathbf{w} \mathbf{w}^\top \rangle \boldsymbol{\phi}_i - \boldsymbol{\phi}_i^\top \langle \mathbf{w} \rangle \langle \mathbf{w} \rangle^\top \boldsymbol{\phi}_i \\ &= \boldsymbol{\phi}_i^\top \mathbf{C}_i \boldsymbol{\phi}_i\end{aligned}$$

where all these expectations are taken under the posterior density,  $p(\mathbf{w}|\mathbf{t}, \mathbf{X}, \sigma^2, \alpha)$ .

# Reading

- Section 3.7–3.8 of Rogers and Girolami (pg 122–133).
- Section 3.4 of Bishop (pg 161–165).

# References I

- C. M. Bishop. *Pattern Recognition and Machine Learning*. Springer-Verlag, 2006. [[Google Books](#)] .
- S. Rogers and M. Girolami. *A First Course in Machine Learning*. CRC Press, 2011. [[Google Books](#)] .