

# Basis Functions

MLAI: Week 4

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# Review

- ▶ Last time: explored least squares for univariate and multivariate regression.
- ▶ Introduced matrices, linear algebra and derivatives.
- ▶ This time: introduce *basis functions* for non linear regression models.

# Outline

Basis Functions

# Basis Functions

## Nonlinear Regression

- ▶ Problem with Linear Regression— $\mathbf{x}$  may not be linearly related to  $\mathbf{y}$ .
- ▶ Potential solution: create a feature space: define  $\phi(\mathbf{x})$  where  $\phi(\cdot)$  is a nonlinear function of  $\mathbf{x}$ .
- ▶ Model for target is a linear combination of these nonlinear functions

$$f(\mathbf{x}) = \sum_{j=1}^K w_j \phi_j(\mathbf{x}) \quad (1)$$

# Quadratic Basis

- ▶ Basis functions can be global. E.g. quadratic basis:

$$[1, x, x^2]$$

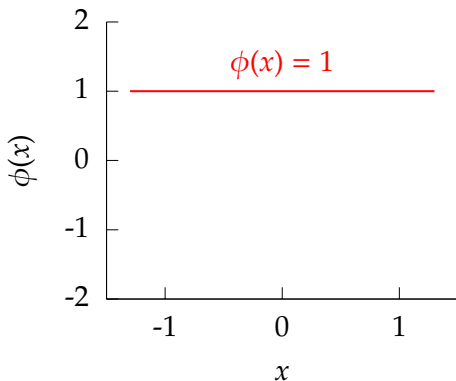


Figure : A quadratic basis.

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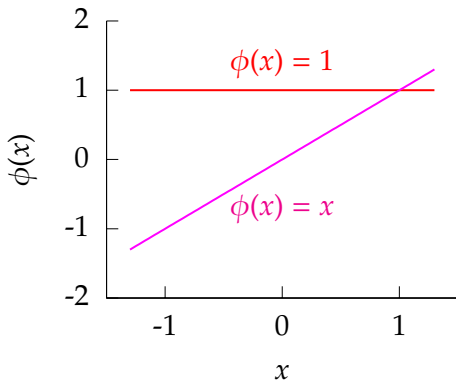


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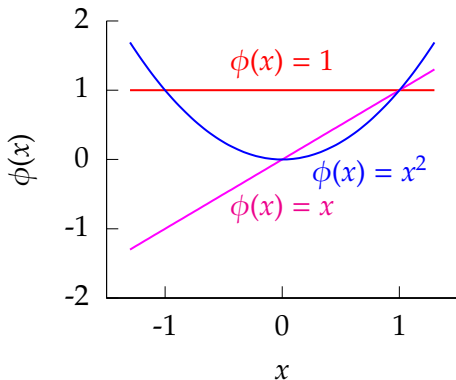


Figure : A quadratic basis.

## Functions Derived from Quadratic Basis

$$f(x) = w_1 + w_2x + w_3x^2$$

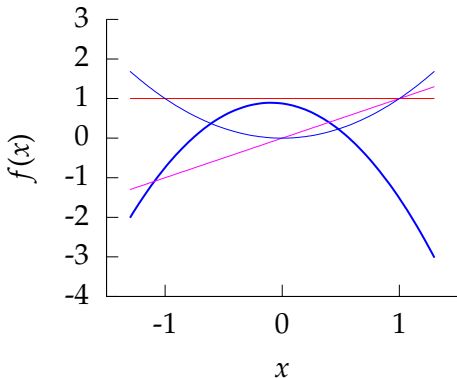


Figure : Function from quadratic basis with weights  $w_1 = 0.87466$ ,  $w_2 = -0.38835$ ,  $w_3 = -2.0058$ .



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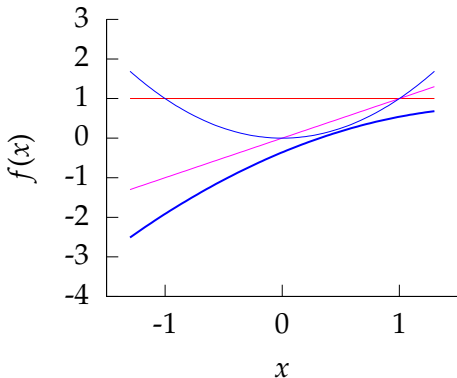


Figure : Function from quadratic basis with weights  $w_1 = -0.35908$ ,  $w_2 = 1.2274$ ,  $w_3 = -0.32825$ .

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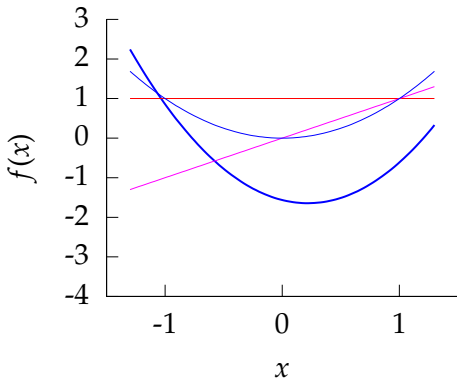


Figure : Function from quadratic basis with weights  $w_1 = -1.5638$ ,  $w_2 = -0.73577$ ,  $w_3 = 1.6861$ .

# Radial Basis Functions

- ▶ Or they can be local. E.g. radial (or Gaussian) basis

$$\phi_j(x) = \exp\left(-\frac{(x-\mu_j)^2}{\ell^2}\right)$$

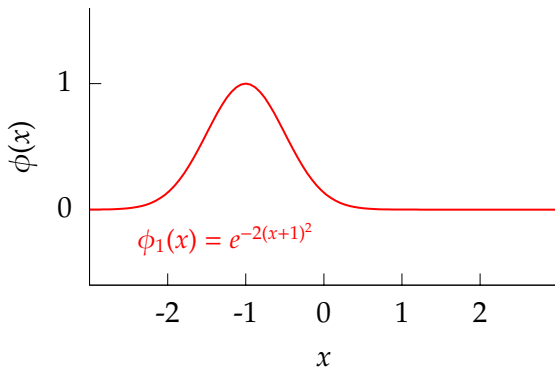


Figure : Radial basis functions.

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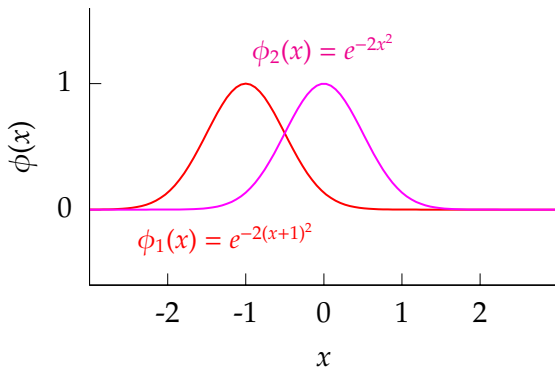


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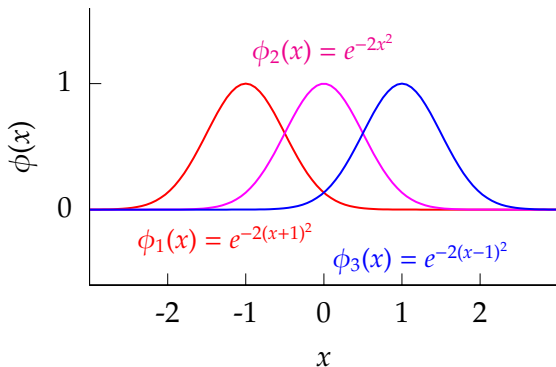


Figure : Radial basis functions.

## Functions Derived from Radial Basis

$$f(x) = w_1 e^{-2(x+1)^2} + w_2 e^{-2x^2} + w_3 e^{-2(x-1)^2}$$

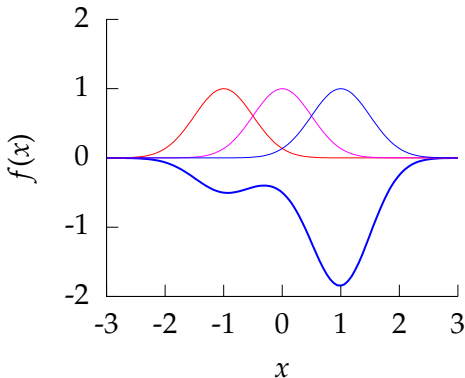


Figure : Function from radial basis with weights  $w_1 = -0.47518$ ,  $w_2 = -0.18924$ ,  $w_3 = -1.8183$ .

## Functions Derived from Radial Basis

$$f(x) = w_1 e^{-2(x+1)^2} + w_2 e^{-2x^2} + w_3 e^{-2(x-1)^2}$$

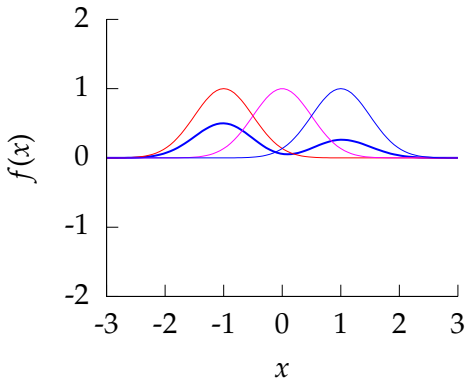


Figure : Function from radial basis with weights  $w_1 = 0.50596$ ,  $w_2 = -0.046315$ ,  $w_3 = 0.26813$ .

## Functions Derived from Radial Basis

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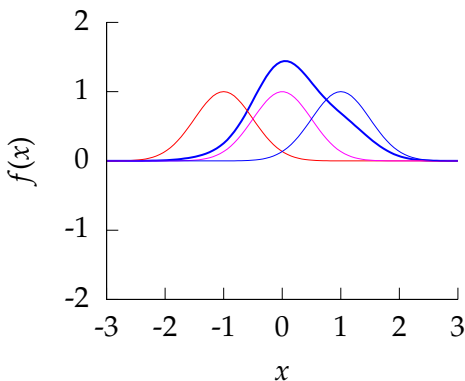


Figure : Function from radial basis with weights  $w_1 = 0.07179$ ,  $w_2 = 1.3591$ ,  $w_3 = 0.50604$ .



# Basis Function Models

- ▶ A Basis function mapping is now defined as

$$f(\mathbf{x}_i) = \sum_{j=1}^m w_j \phi_{i,j} + c$$

# Vector Notation

- ▶ Write in vector notation,

$$f(\mathbf{x}_i) = \mathbf{w}^\top \boldsymbol{\phi}_i + c$$

# Log Likelihood for Basis Function Model

- ▶ The likelihood of a single data point is

$$p(y_i|x_i) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y_i - \mathbf{w}^\top \phi_i)^2}{2\sigma^2}\right).$$

- ▶ Leading to a log likelihood for the data set of

$$L(\mathbf{w}, \sigma^2) = -\frac{n}{2} \log \sigma^2 - \frac{n}{2} \log 2\pi - \frac{\sum_{i=1}^n (y_i - \mathbf{w}^\top \phi_i)^2}{2\sigma^2}.$$

- ▶ And a corresponding error function of

$$E(\mathbf{w}, \sigma^2) = \frac{n}{2} \log \sigma^2 + \frac{\sum_{i=1}^n (y_i - \mathbf{w}^\top \phi_i)^2}{2\sigma^2}.$$

## Expand the Brackets

$$\begin{aligned} E(\mathbf{w}, \sigma^2) &= \frac{n}{2} \log \sigma^2 + \frac{1}{2\sigma^2} \sum_{i=1}^n y_i^2 - \frac{1}{\sigma^2} \sum_{i=1}^n y_i \mathbf{w}^\top \phi_i \\ &\quad + \frac{1}{2\sigma^2} \sum_{i=1}^n \mathbf{w}^\top \phi_i \phi_i^\top \mathbf{w} + \text{const.} \\ &= \frac{n}{2} \log \sigma^2 + \frac{1}{2\sigma^2} \sum_{i=1}^n y_i^2 - \frac{1}{\sigma^2} \mathbf{w}^\top \sum_{i=1}^n \phi_i y_i \\ &\quad + \frac{1}{2\sigma^2} \mathbf{w}^\top \left[ \sum_{i=1}^n \phi_i \phi_i^\top \right] \mathbf{w} + \text{const.} \end{aligned}$$

# Multivariate Derivatives Reminder

- ▶ We will need some multivariate calculus.

$$\frac{d\mathbf{a}^\top \mathbf{w}}{d\mathbf{w}} = \mathbf{a}$$

and

$$\frac{d\mathbf{w}^\top \mathbf{A} \mathbf{w}}{d\mathbf{w}} = (\mathbf{A} + \mathbf{A}^\top) \mathbf{w}$$

or if  $\mathbf{A}$  is symmetric (*i.e.*  $\mathbf{A} = \mathbf{A}^\top$ )

$$\frac{d\mathbf{w}^\top \mathbf{A} \mathbf{w}}{d\mathbf{w}} = 2\mathbf{A} \mathbf{w}.$$

# Differentiate

Differentiating with respect to the vector  $\mathbf{w}$  we obtain

$$\frac{\partial L(\mathbf{w}, \beta)}{\partial \mathbf{w}} = \beta \sum_{i=1}^n \phi_i y_i - \beta \left[ \sum_{i=1}^n \phi_i \phi_i^\top \right] \mathbf{w}$$

Leading to

$$\mathbf{w}^* = \left[ \sum_{i=1}^n \phi_i \phi_i^\top \right]^{-1} \sum_{i=1}^n \phi_i y_i,$$

Rewrite in matrix notation:

$$\sum_{i=1}^n \phi_i \phi_i^\top = \mathbf{\Phi}^\top \mathbf{\Phi}$$

$$\sum_{i=1}^n \phi_i y_i = \mathbf{\Phi}^\top \mathbf{y}$$

# Update Equations

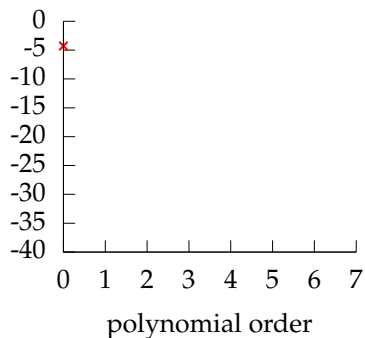
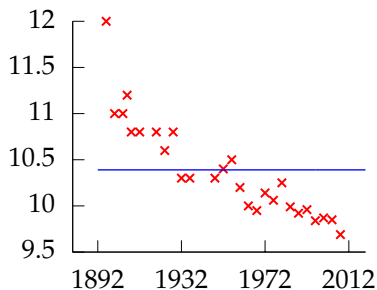
- ▶ Update for  $\mathbf{w}^*$ .

$$\mathbf{w}^* = (\Phi^\top \Phi)^{-1} \Phi^\top \mathbf{y}$$

- ▶ The equation for  $\sigma^{2*}$  may also be found

$$\sigma^{2*} = \frac{\sum_{i=1}^n (y_i - \mathbf{w}^{*\top} \phi_i)^2}{n}.$$

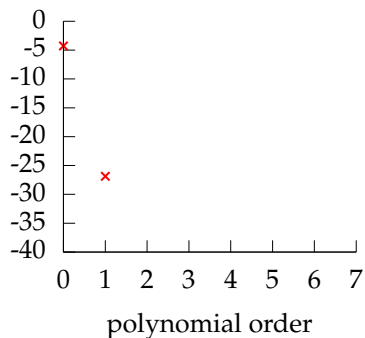
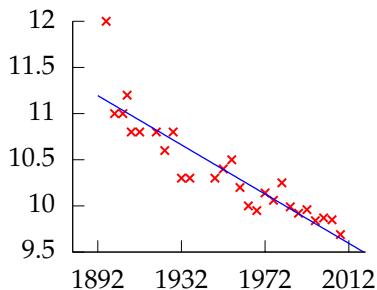
# Polynomial Fits to Olympics Data



*Left: fit to data, Right: model error.* Polynomial order 0, model error  $-4.2717$ ,  $\sigma^2 = 0.268$ ,  $\sigma = 0.518$ .

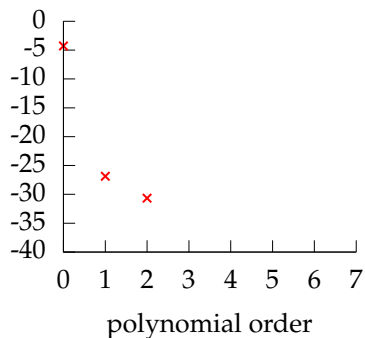
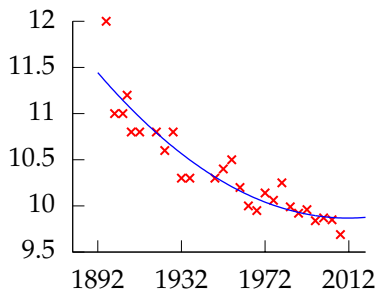


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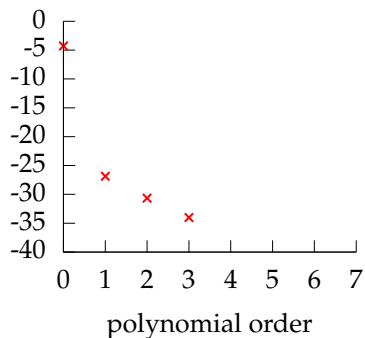
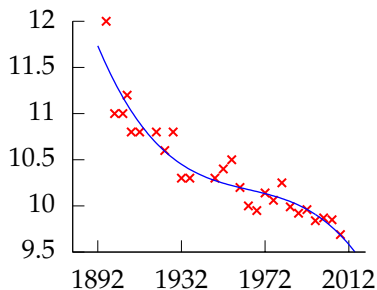
*Left: fit to data, Right: model error.* Polynomial order 1, model error -26.86,  $\sigma^2 = 0.0503$ ,  $\sigma = 0.224$ .

## Polynomial Fits to Olympics Data



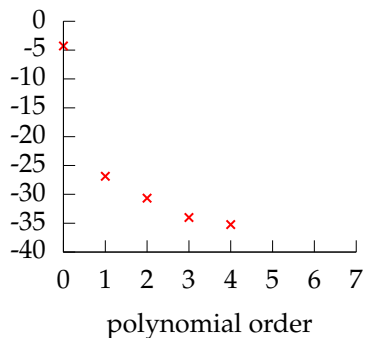
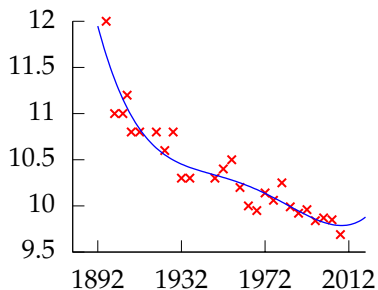
*Left: fit to data, Right: model error. Polynomial order 2, model error -30.662,  $\sigma^2 = 0.0380$ ,  $\sigma = 0.195$ .*

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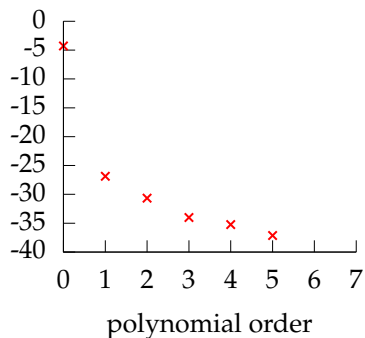
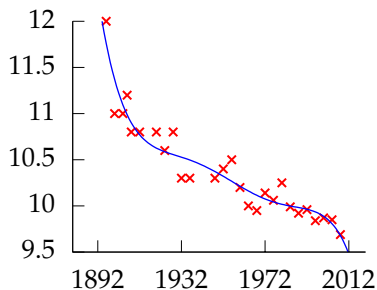
*Left: fit to data, Right: model error. Polynomial order 3, model error -34.015,  $\sigma^2 = 0.0296$ ,  $\sigma = 0.172$ .*

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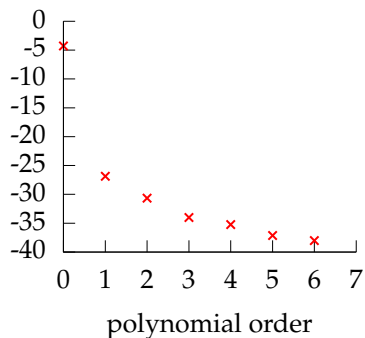
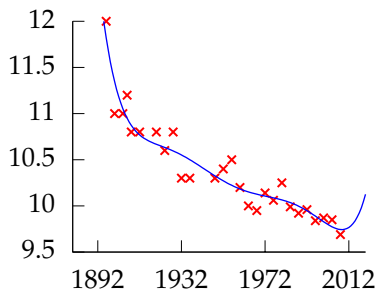
*Left: fit to data, Right: model error. Polynomial order 4, model error -35.231,  $\sigma^2 = 0.0271$ ,  $\sigma = 0.165$ .*

## Polynomial Fits to Olympics Data



*Left: fit to data, Right: model error. Polynomial order 5, model error -37.138,  $\sigma^2 = 0.0235$ ,  $\sigma = 0.153$ .*

# Polynomial Fits to Olympics Data



*Left: fit to data, Right: model error. Polynomial order 6, model error -38.016,  $\sigma^2 = 0.0220$ ,  $\sigma = 0.148$ .*

# Reading

- ▶ Chapter 1, pg 1-6 of Bishop.
- ▶ Section 1.4 of Rogers and Girolami.
- ▶ Chapter 3, Section 3.1 of Bishop up to pg 143.

# References I

C. M. Bishop. *Pattern Recognition and Machine Learning*. Springer-Verlag, 2006. [\[Google Books\]](#) .

S. Rogers and M. Girolami. *A First Course in Machine Learning*. CRC Press, 2011. [\[Google Books\]](#) .